

Reshaping SRF Cavity Resonance Management with Smart Techniques

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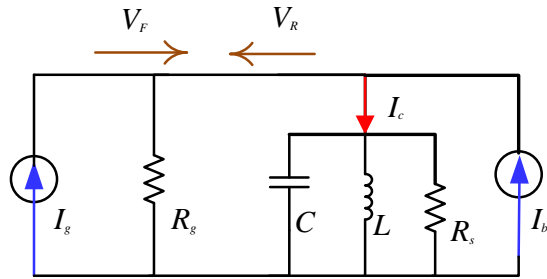


SRF Cavity

DMD

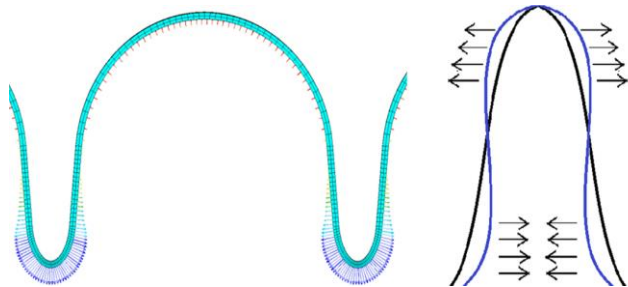
Test Results

■ Cavity Circuit model



Linear System

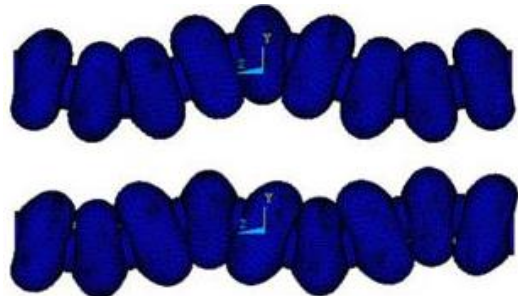
■ Lorentz pressure distribution on cavity wall



Nonlinear Force

$$P = \frac{1}{4} (\epsilon_0 E^2 - \mu_0 H^2)$$

■ Mechanical Modes: ω_m, Q_m, K_m

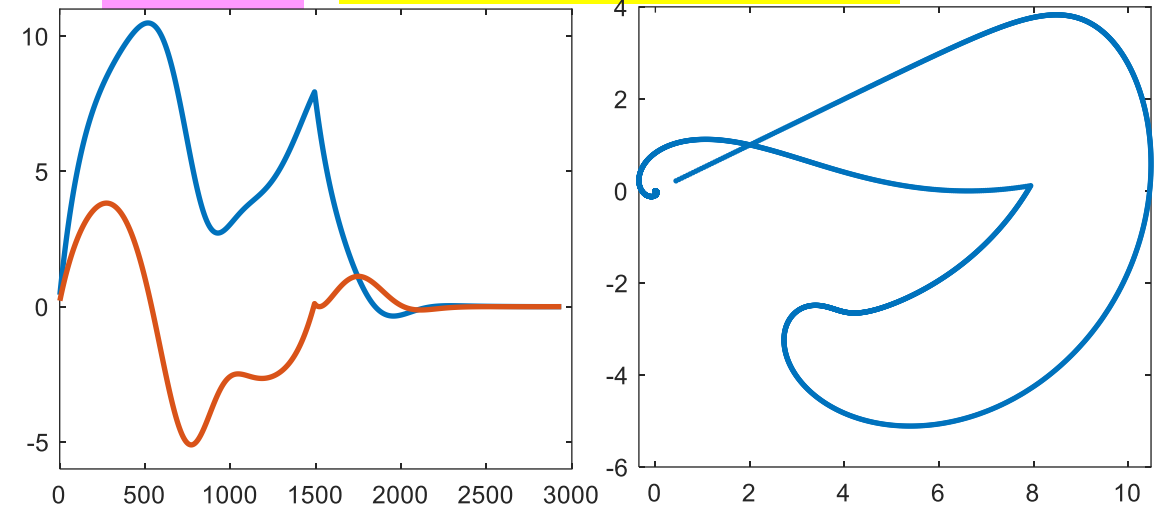


Electromagnetic field

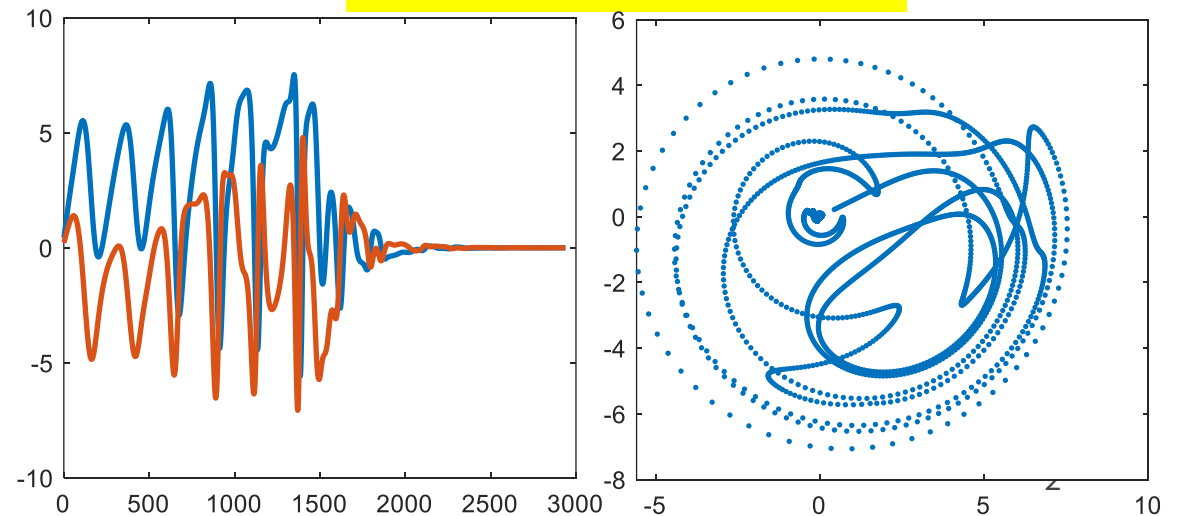
Vibration

$\times 5K_L$

Single Mechanical Mode



5 Mechanical Modes



DMD: Dynamic Mode Decomposition

$$\frac{d}{dt} \mathbf{x}(t) = F(\mathbf{x}(t)) \quad \mathbf{x}_{k+1} = F(\mathbf{x}_k) \quad F \approx f \text{ based on data}$$

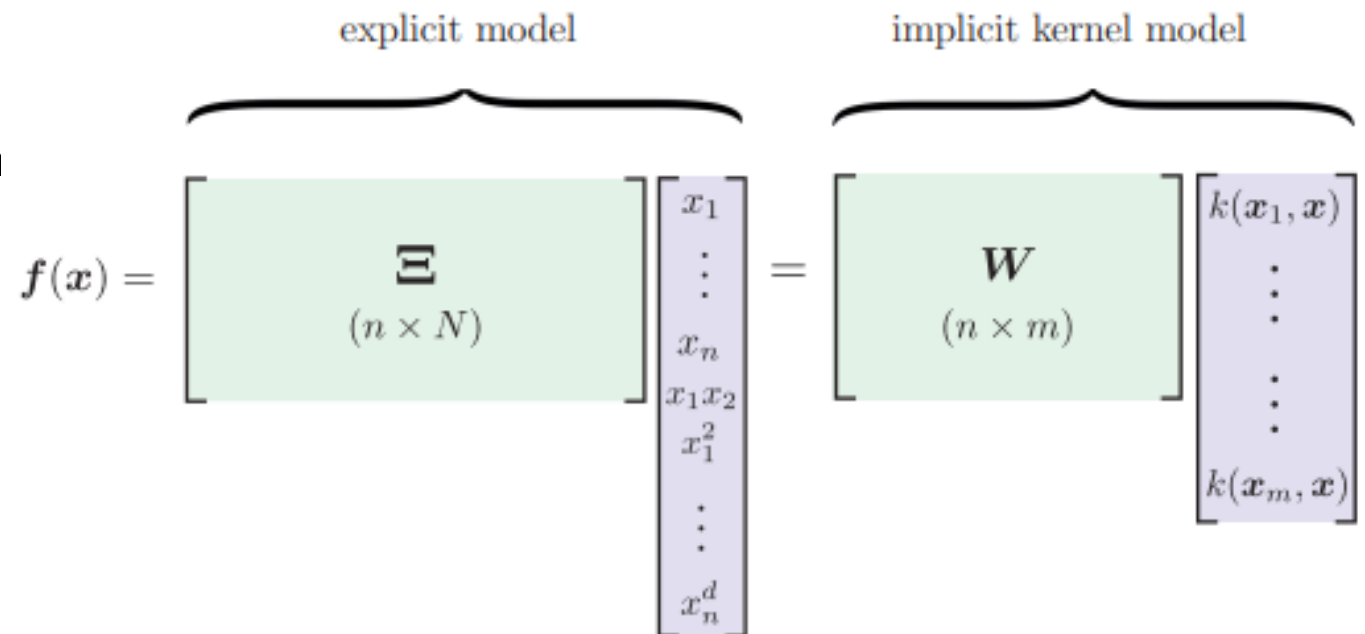
$\mathbf{x}_k = [\mathbf{a}_k \ \mathbf{b}_k]^T$: system status and actuator inputs

Linear system: $\mathbf{x}_{k+1} = W \mathbf{x}_k$

Mapping nonlinear problem in large state dimension with kernel function

$$f \approx \sum_{j=1}^N \xi_j \phi_j(\mathbf{x}) = \Xi \phi(\mathbf{x}) = W k(\mathbf{X}, \mathbf{x})$$

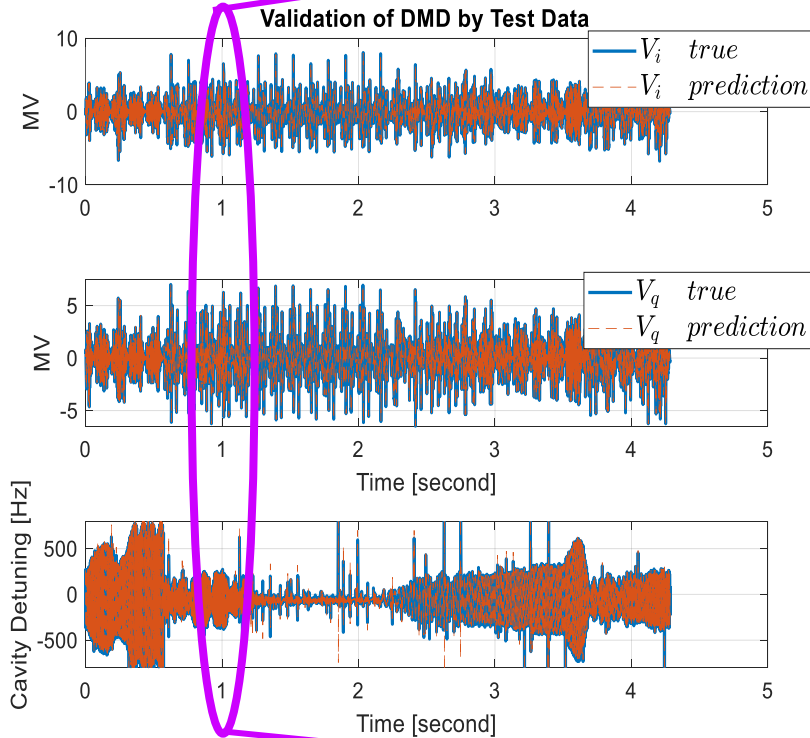
- ϕ : the feature library of N candidate term that may describe the dynamics
- Ξ : the coefficients that determine which feature terms are active and what proportions.
- k : kernel function
- Data matrices: $X = [x_1 \ x_2 \ \dots \ x_m]$



SRF Cavity

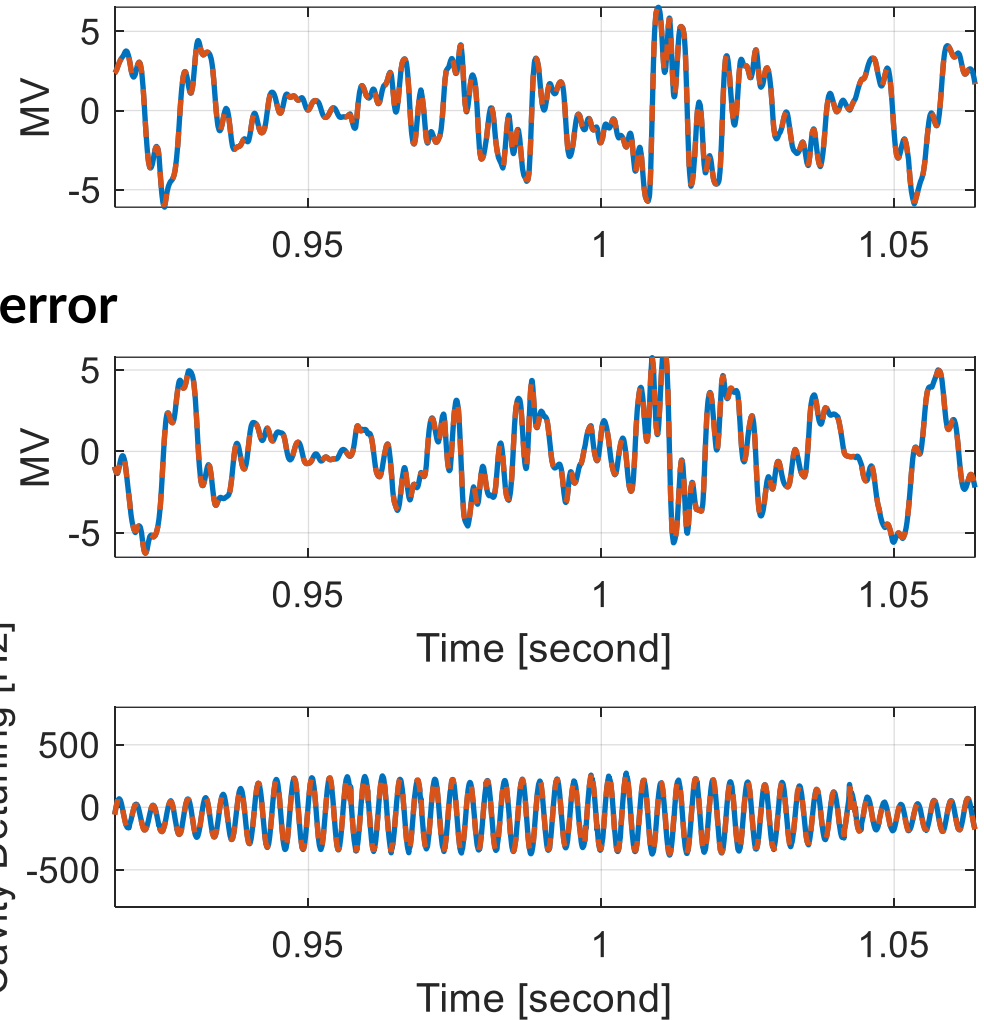
DMD

Test Results



~ 2.5% test error

Cavity Detuning [Hz]



Active Resonance Controller

- Simulation with 32 mechanical modes
- Cavity half bandwidth: 16.25 Hz
- Detune std: ~ 1 Hz

