

Integration of Multi-Objective Genetic Algorithm and neural networks in linac optimization



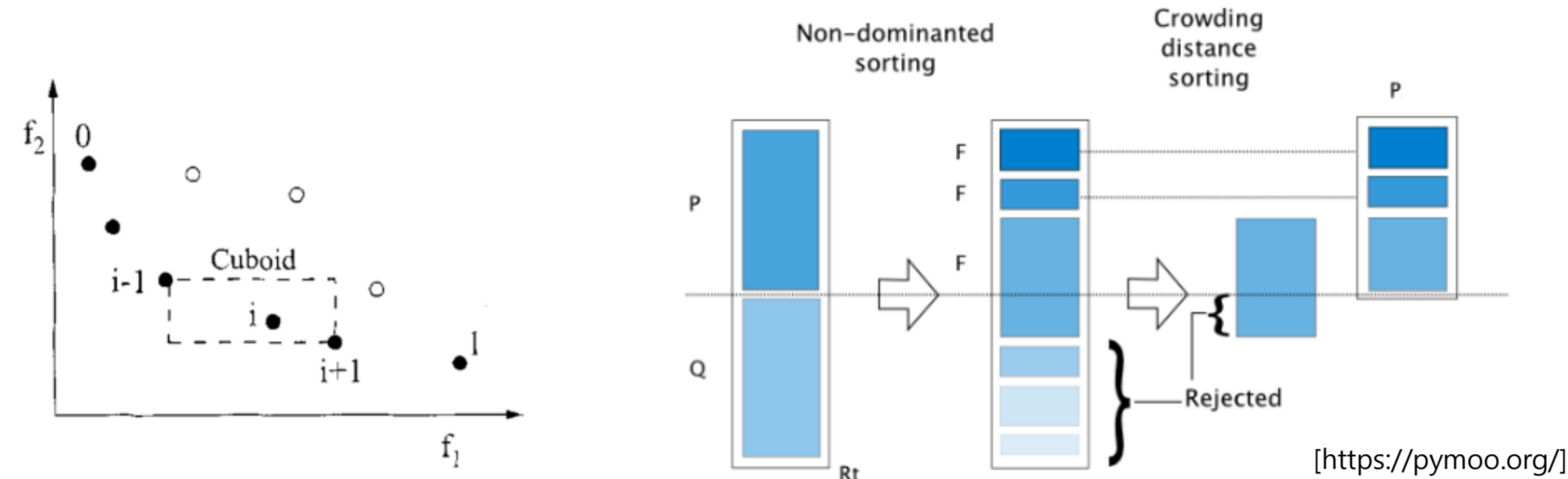
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Abstract

Multi-Objective Genetic Algorithm(MOGA) is one of promising approach for optimizing nonlinear beam dynamics in accelerators. For explorative problems that have many variables and local optima, however the performance of MOGA is not always satisfactory. To improve the efficiency of optimization in linac beam line, we propose a novel integration of MOGA and neural networks. The neural network is trained with the data produced in the evolution of the MOGA. The objective values of the offspring are estimated with the trained neural network. Based on the estimated results, those offspring are ranked with the nondominated sorting method. We therefore propose a novel Machine Learning technique in which nonlinear tracking is replaced by two well-trained neural networks to beam line lattice.

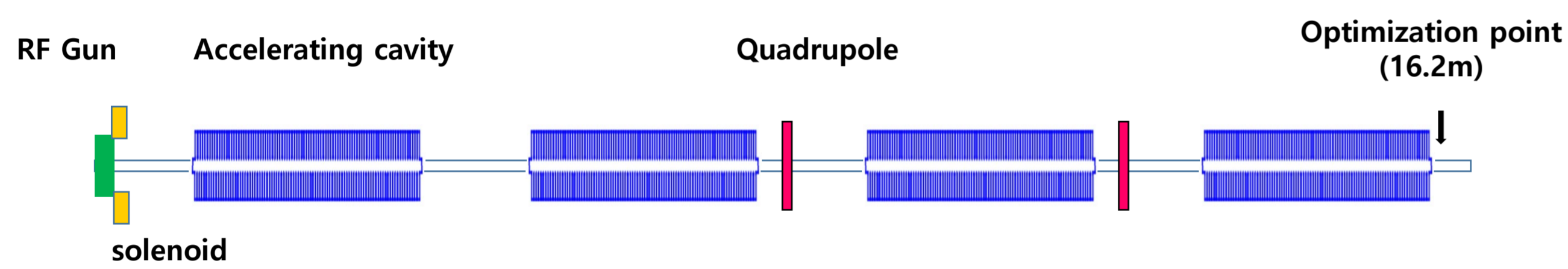
Multi-Objective Genetic Algorithm (NSGA-II algorithm)

NSGA-II: Non-dominated Sorting Genetic Algorithm



The algorithm follows the general outline of a genetic algorithm with a modified mating and survival selection. In NSGA-II, first, individuals are selected frontwise. By doing so, there will be the situation where a front needs to be split because not all individuals are allowed to survive. In this splitting front, solutions are selected based on crowding distance. The crowding distance is the Manhattan Distance in the objective space. However, the extreme points are desired to be kept every generation and, therefore, get assigned a crowding distance of infinity. Furthermore, to increase some selection pressure, NSGA-II uses a binary tournament mating selection. Each individual is first compared by rank and then crowding distance.

layout of the electron linac



- RF photocathode gun
- 4 accelerating structures
- One solenoid & 2 quadrupole

Optimization requirement (problem functions and variables)

Objectives (3)	Unit
Normalized rms emittance X&Y	Minimization mm-mrad
rms energy spread	Minimization keV

Constraint (7)	Unit
Beam size X & Y (rms)	< 0.3 mm
Divergence X&Y	< 0.2663 mrad
Bunch length	< 1.0 mm
Transmission rate	>99.99 %
Average energy	>200 MeV

Variables (6)	range	unit
RF gun phase	0~360	degree
Acc1&2 phase	0~360	degree
Acc3&4 phase	0~360	degree
Solenoid	0.15~0.21	T
Quad 1&2	1~3(-4~-1)	T/m

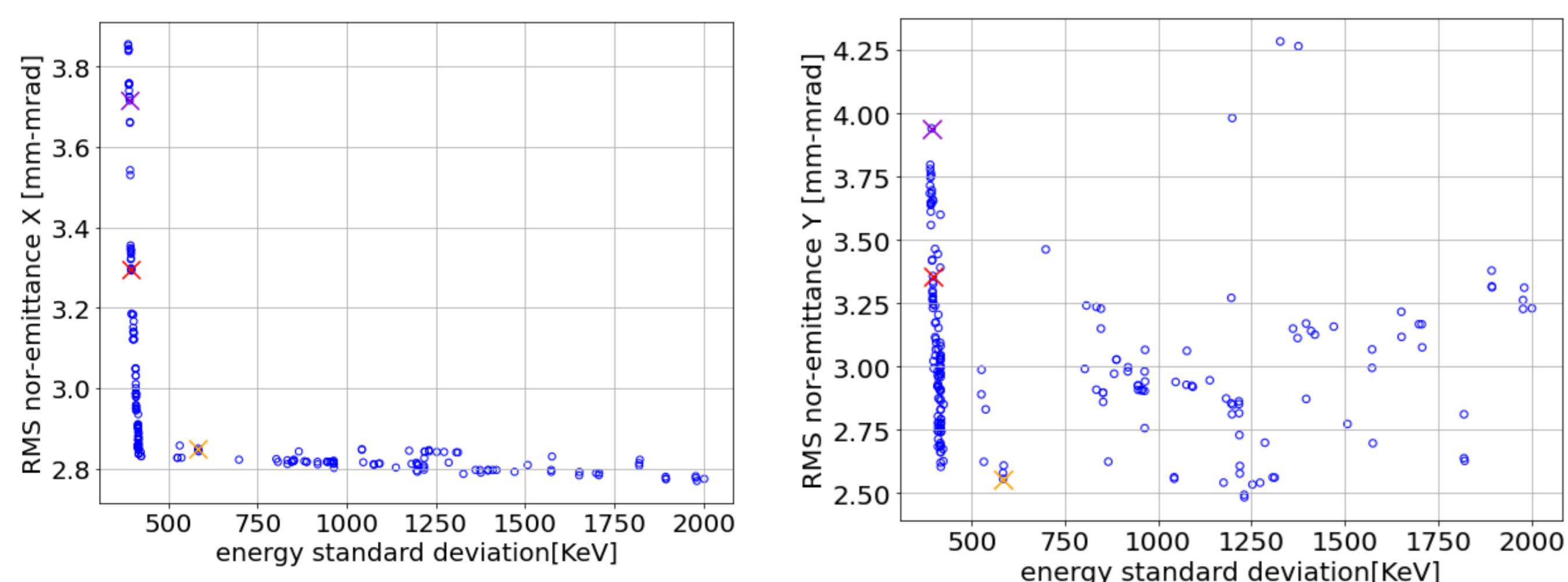
Beam tracking code

: ASTRA code
Optimization algorithm
 : Multi-Objective Genetic Algorithm (MOGA)
Tool
 : pymoo (base : python)

Population : 500 / offspring : 250/ generation : 300

Result of optimization

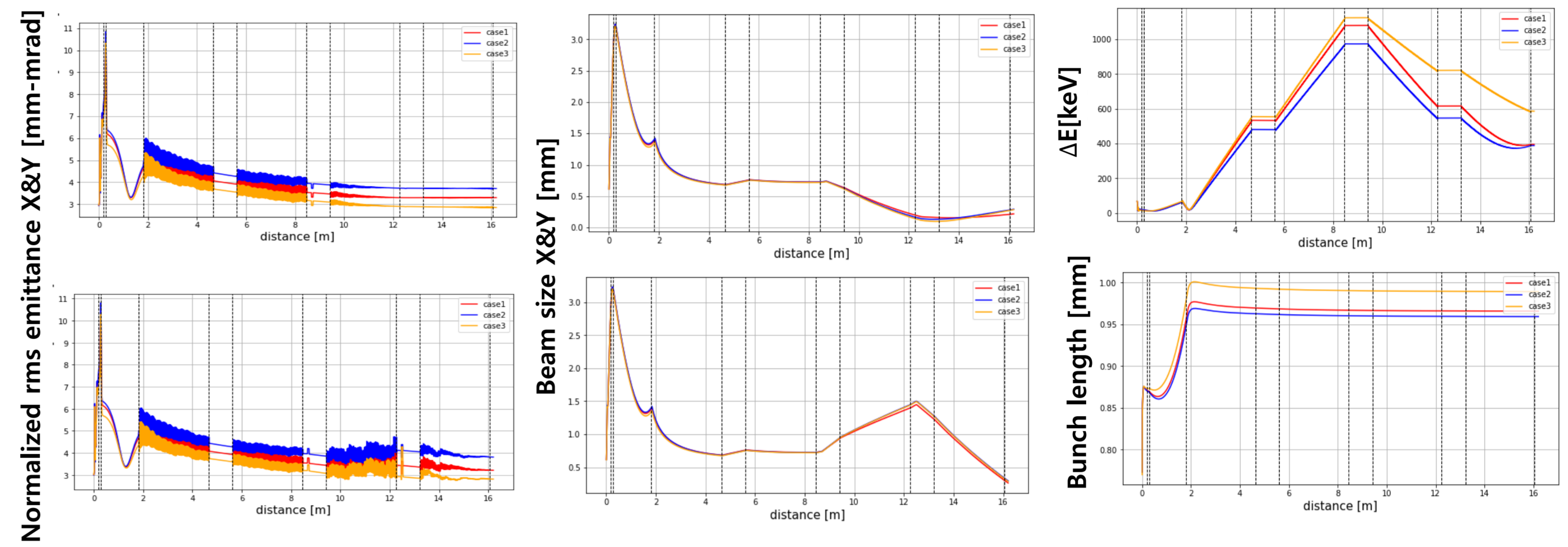
Objective space



	longitudinal	Transverse	
	Energy spread	Emittance X	Emittance Y
Case1	0.5	0.25	0.25
Case2	0.8	0.1	0.1
case3	0.3	0.35	0.35

The optimized Pareto front data in objective space
 The three cases selected to compare beam tracking simulation based on the importance of objectives
 The objective weights are determined by the ratios of the three objectives

beam tracking simulation



mode	Energy spread [keV]	emittanceX [mm-mrad]	geometric emittance X [nm]	emittanceY [mm-mrad]	geometric emittance Y [nm]	Xrms [mm]	Yrms [mm]	L_bunch [mm]	Transmission rate [%]	average E [MeV]
Case1	381.50	3.2990	8.44	3.2145	8.18	0.21760	0.26149	0.96584	100	200.16
Case2	372.17	3.7122	9.52	3.8144	9.71	0.29162	0.29447	0.95932	100	200.61
Case3	584.24	2.8520	7.37	2.8147	7.21	0.28593	0.28566	0.98924	100	200.92

<1MeV(0.5%) <10nm <10nm < 1mm

machine learning using MOGA data

Input data : RF gun phase, acc1&2 phase, acc3&4 phase : 3
 Output data : rms energy spread : 1
 Total data(train/test) : 10000 (7000/3000)
 Moga generation : 200~220
 Layer : 6

Case 1 :
 train data transform type : normalize
 Activation function : ReLU (Rectified Linear Unit)

Case 2 :
 train data transform type : raw data
 Activation function : Tanh (Hyperbolic Tangent)

Output : energy spread
 RF gun phase : 120~210 (step : 10)
 Acc1&2 phase and acc 3&4 phase fix

	case1	case2
train data	2553.077881	353.7229309
2602.841309	353.7229309	353.7229309
2652.60498	353.7229309	353.7229309
2702.368164	353.7229309	353.7229309
2752.131836	353.7230835	353.7230835
2801.89502	353.7247009	353.7247009
2851.658203	353.724823	353.724823
2901.421875	353.724823	353.724823
2951.185547	353.724823	353.724823
3000.948486	353.724823	353.724823

Input data : RF gun phase, acc1&2 phase, acc3&4 phase : 3
 Output data : rms energy spread : 1
 Total data(train/test) : 10000 (7000/3000)
 layer : 6
 Activation function : Tanh

Training data range

generation	14	200	281
RF gun	67.26912	0.049265	0.049265
acc1&2	96.30259	1.124652	0.896699
acc3&4	349.5431	8.961445	10.19618
solenoid	0.075308	1.84E-05	1.84E-05
quad 1	4.732247	0.035038	0.041793
quad 2	4.905732	0.029668	0.026938

Moga generation (step :20)
 RF gun phase (120~210)

generation	14	200	281
1871.229492	353.7229309	398.4751587	398.4760132
1871.229492	353.7229309	398.4751587	398.4760132
1871.229492	353.7229309	398.4751587	398.4760132
1871.229492	353.7229309	398.4751587	398.4760132
1871.229492	353.7230835	398.4752197	398.4760132
1871.229492	353.7247009	398.4762573	398.4761047
1871.229492	353.724823	398.4768066	398.4768066
1871.229492	353.724823	398.4768066	398.4768066
1871.229492	353.724823	398.4768066	398.4768066
1871.229492	353.724823	398.4768066	398.4768066

Moga generation (281)
 Acc1&2 phase(0~100)

generation	281
398.4760132	398.4760132
398.4760132	398.4760132
398.4760132	398.4760132
398.4760132	398.4760132
398.4760132	398.4760132
398.4761047	398.4761047
398.4768066	398.4768066
398.4768066	398.4768066
398.4768066	398.4768066
398.4768066	398.4768066

Input data : RF gun phase, acc1&2 phase, acc3&4 phase : 6
 Output data : rms energy spread (or emittance) : 1
 Total data(train/test) : 10000 (7000/3000)
 Activation function : Tanh

RF gun phase (120~210)
 Train output data
 Energy spread : 398.80032
 Emittance : 3.7936825

ASTRA tracking simulation output

RF gun phase	energy spread	emittance x	transmission rate
210	781.71	6.0387	100
200	568.66	7.1091	100
190	1882.2	10.614	85.95
180	2791.1	2.3695	28.67

The output values for input variables reflecting the train data are different from the results of beam tracking simulation.

Future plan

- We need to find the reason why the train results and beam tracking simulation results are different.
 - : Increasing the number of train data
 - : Obtain data suitable for machine learning from moga
 - : Adjusting other hyper-parameters used in machine learning (number of layers, Hidden_size, Epochs, Learning_rate, Data_rate, etc.)