ML-Based Model Calibration Methods

For Accelerator Physics Simulations

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High Performance Accelerator Models Are Central to AI/ML Efforts



Fast-Executing, Accurate System Models



Accelerator simulations that include nonlinear and collective effects are powerful tools, but they can be computationally expensive



Model Calibration





Model Calibration





Model Calibration



Outline

- Framing the problem
- Three examples:
 - MCMC at HiRES (LBNL)
 - Learning scaling factors & offsets at LCLS (SLAC)
 - Ongoing FACET-II (SLAC) model calibration

FACET-II (SLAC)

Outlook

Laser



The Inverse Problem for Model Calibration

 $\arg \min \|d_{obs} - f(x_1, x_2, \dots, x_n))\|_1$

- Zeroth order solution: parameter scan
 - But with multiple dimensions, becomes untenable
- Considerations: choosing an approach
 - Model execution time/cost
 - Model types
 - Desired information
 - Amount of data





0.50

2.00

1.75

https://blog.paperspace.com/intro-to-optimization-in-deep-learning-gradient-descent/

1.00

0.75 0.50

0.25 0.00

-0.25 X

0.50

-0.75

Full Prob. Distributions: Markov Chain Monte Carlo (MCMC)



- Initialize walkers and have them update based on probability of proposed move
- Goodman and Weare "stretch move" proposal [1] (with Metropolis-Hastings [2] acceptance rule)
- Markov chain: future step depends only on current step

Advantages & Disadvantages

- Full posterior probability distribution for optimization variables
- Generally slower than optimization
 - Requires fast-executing model

SLAC

[2] W. Hastings, Biometrika, 57: 97-109 (1970)

[1] J. Goodman and J. Weare, Communications in applied mathematics and computational science 5, 65 (2010)

Example Problem and the Prescription

Example Problem



HiRES (LBNL) gun: matching beam dynamics (GPT) simulation to real data (using NN surrogate model)

Find the following parameters based on beam second order moments in solenoid scan:

- Cathode MTE
- Beam energy
- Solenoid quadrupole moment
- Solenoid skew quadrupole moment
- Cathode recession depth



The Prescription

- Run GPT in parallel for rough parameter scan
- Train NN surrogate model
- MCMC sampling of surrogate model to match model to data





4.75

4.8

MCMC Error

0.001

0.002

0.004

0.003

0.003

4.85

Comparison with local optimization

LCLS Injector Calibration with a NN

- Trained neural network model on IMPACT-T
 - MOGA on the emittance and random sampling
- Freeze main representation, learn scaling and offset via back-propagation
- Linear approach: interpretability
 - Fast way of identifying possible error sources simultaneously
 - Similar to transfer learning, but interpretable







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LCLS Example: Model Calibration for BO with NN Priors

•Quality of the prior mean model is important to BO performance

•Need to account for all changes in parameters/inputs over time

•Number of required samples depends heavily on the data distribution

DatasetN. Data Pointstrain36020val17671test10011







T. Boltz et al. arXiv:2403.03225

SLAC

ISIS Neutron and Muon Source

Science and Technology

Facilities Counci

Well-distributed data

- Bayesian Exploration for efficient exploration:
 - Time efficient
 - Well-distributed data
- FACET-II: 2 hrs for 10 variables compared to 5 hrs for 4 variables with N-D parameter scan
- Data was used to train neural network model of injector response predicting x-y beam images.
- GP ML model from exploration predicts emittance and match.



transverse beam profile



In Progress: FACET-II Model Calibration



Second-Order Moments from Solenoid Scan (Below)

Selected Images from Solenoid Scan (Right)





mm







FACET-II & User Needs

- High charge beams --> plasma experiments
- Want start-to-end simulations so users can optimize their experiments

-2













Recall Wednesday's talk from R. Lehe

FACET-II & Multifidelity Optimization



- Information theoretic approach to simulations
- Learn correlations between different model fidelities
- Use multi-fidelity Bayesian optimization to select model fidelity



SLAC

Number of Particles (N)	2e4	2e5	2e6
Space Charge Grid Size	16	32	64
Execution time	~1 min	~2.5 min	~25 min
$\sigma_{\rm x}$ (um)	1026	1018	1017
$\sigma_{ m y}$ (um)	654	623	614
Norm x emit (um)	9.26	8.87	8.77

N= 250 · 2e4 2.0 1.5 1.0 0.5 y (mm) 0.0 -0.5 -1.0 -1.5 -2.0 500 -3 3 -2 x (mm)pC/mm 500 N= pC/mm 2e5 1 y (mm) 0 -2 -3 -2 pC/mm x (mm)N= 500 DC/mm 2e6 y (mm) -1 -2 -3 -2 500 x (mm)pC/mm

Future: Full Integration of AI/ML Optimization, Modeling, and Physics Simulations



Part of a larger effort



Differentiable simulations, including Bmad



Interoperable standards and tools for end-to-end accelerator simulations



Model calibration for RHIC

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