

# Piezo driver for spoke and elliptical cavities of ESS project linac production and installation status



**EUROPEAN SPALLATION** SOURCE

<u>W. Cichalewski<sup>1</sup>, K. Kłys<sup>1</sup> J. Niedzialek<sup>1</sup> A. Mielczarek<sup>1</sup> D. Makowski<sup>1</sup> F. Pawlowski<sup>1</sup> P. Perek<sup>1</sup> R. Tomala<sup>1</sup> M. Jensen<sup>2</sup> A. Svensson<sup>2</sup></u>

<sup>1</sup> Technical University of Łódź, Department of Microelectronics and Computer Science (DMCS), Łódź, Poland <sup>2</sup> European Spallation Source, Lund, Sweden

### Abstract

The MTCA 4 based piezo driver has been proposed and developed by the LUT-DMCS engineers as a Polish in-kind to the ESS project. The driver is capable to drive two independent channels dedicated to a single piezo tuner in a single cavity. It has been designed to work for elliptical resonators (M-Beta and H-Beta) with 0 to 200 V output voltage range. Additionally, it can be reconfigured to work in any bipolar or asymmetric range between -190 to 190 V. That is why it will be installed also for the spoke accelerating structures of the same linac. The current contribution presents the latest status of the piezo driver production and installation in the ESS accelerator. Results from the hardware evaluation and initial tuning performance achieved at the Test Stand 2 facility are discussed too.

### Piezo Driver Design and parameters



# Piezo Driver and PPSM production

- The mass production consisted of 2 pre-production pieces and 118 pieces of final production,
- The 2 pre-production modules have been used for the production quality check and possible corrections and improvements report preparation,
- The final production has been released after pre-production verification and corrections/improvements report acceptance,
- Post-production testing included four phases: visual inspection, management power test, thermal pads and shielding installation, verification in local dedicated test stand,
- Imperfections spotted in each phase resulted in vendor actions to remove error,



Figure 10: Piezo driver RTM board mass production version



Figure 1: Piezo driver implementation diagram

Minister of Education

and Science

# Main features:

- 2 independent channels operation,
- operation as an actuator or a sensor,
- suitable for all kind of cavities in the cold linac,
- synchronization with the linac timing,
- remote reconfiguration accessible,
- MTCA.4 compatible,
- separated Piezo Power Supply Module with integrated diagnostics and control,
- health status and diagnostics integrated on the RTM module and accessible from the AMC side.

DEVICE LIBRARY LO RTM LIBRAR

Figure 2: SW/FW diagram

Figure 4: TS2 bunker with the CM03

Figure 5: Piezo controller HW for

TS2 installation

- Parameters :
- output voltage range: 0 to +200V (-40 to 160V for spokes),
- controller bandwidth DC-1kHz,
- repetition rate 14 Hz,
- Max. power 30W,
- PowerSupply voltage -/+ 100V,
- Actuator: sampling freq. 1MHz, No of samples: 30k, resolution 16 bits,
- Sensor: sampling freq. 1MHz, No of samples: 30k, resolution 16 bits, input voltage -/+1V, impedance: 10kOhm,
- piezo capacitance (room temp.) 6.6 to 11 uF.

- PPSM modules assembled in-house. • dedicated internal PCB designed for the power supply control and various sensors monitoring,
- 120 pcs completed and tested,
- due to the semiconductor crisis two versions have been designed verified and produced,
- post-production testing performed on the dedicated test-stand,
- dedicated inventory for HW provided.

### Piezo driver installation

Piezo driver installation scope:

- Delivery of 120 pcs of the piezo driver RTM module to ESS,
- Delivery of 120 pcs of the piezo driver external power supply module to ESS,
- Delivery of 120 RTM to PS connection cables to ESS,
- Hardware installation for the M-Beta LLRF systems (36 pcs),
- Hardware installation for the H-Beta LLRF systems (20 pcs),
- Hardware installation for the Spoke LLRF systems (26 pcs) – outside current IK scope,
- Verification of the installed systems: • Visual inspection,
  - Test of the AC and DC excitation readouts from the driver,



top-view (without cover)



Figure 12: PPSM assembly

Aisle	System	HPD ID	RTM Carrier ID		PPSM ID	Tested		Visual inspection	Comments
						DC/AC	Cav Sim test		
MBL- 010	E01	B011	478	v1.57	A002	ОК	ОК	Ok	piezo cables not connected
	E02	B013	490	v1.57	A003	-	ОК	Ok	
	E03	B014	477	v1.58	A001	ОК	ОК	Ok	
	E04	B015	474	v1.57	A004	ОК	REF	Ok	
MBL- 020	E01	B016	494	v1.57	A014	ОК	ок	Ok	no labels for HPD-PPSM cable
	E02	B017	471	v1.57	A013	ОК	ок	Ok	no labels for HPD-PPSM cable
	E03	B018	499	v1.57	A015	ОК	ОК	Ok	no labels for HPD-PPSM cable
	E04	B019	495	v1.57	A012	ОК	ок	Ok	no labels for HPD-PPSM cable
MBL- 030	E01	B020	483	v1.57	A009	ОК	ERR, no RF	Ok	no labels for HPD-PPSM cable
	E02	B022	496	v1.57	A010	ОК	ок	Ok	no labels for HPD-PPSM cable
	E03	B023	492	v1.57	A011	ОК	ок	Ok	no labels for HPD-PPSM cable
	E04	B024	484	v1.57	A008	ОК	ок	Ok	no labels for HPD-PPSM cable
MBL- 040	E01	B025	485	v1.58	A018	ОК	REF	Ok	
	E02	B026	472	v1.57	A016	ОК	ок	Ok	
	E03	B027	493	v1.57	A112		In operation	Ok	in operation
	E04	B028	497	v1.57	A017	ОК	ОК	Ok	
MBL- 050	E01	B029	479	v1.57	A019	ОК	REF	Ok,	piezo cables not connected
	E02	B030	491	v1.57	A020	ОК	In operation	Ok	
	E03	B031	473	v1.57	A023	ОК	ок	Ok	
	E04	B032	501	v1.57	A024	ОК	ОК	Ok	
MBL- 060	E01	B033	481	v1.57	A025	ОК		Ok	piezo cables not connected
	E02	B034	489	v1.57	A026	ОК		Ok	
	E03	B035	475	v1.57	A027	ОК		Ok	
	E04	B036	488	v1.57	A028	ОК		Ok	
MBL- 070	E01	B037	480	v1.58	A029	ОК		Ok	piezo cables not connected
	E02	B038			A030	ОК		Ok	

### Figure 13: M-Beta installation results table

### Piezo Driver evaluation with elliptical cavities

- Piezo Driver prototypes evaluated @FREIA laboratory with the spoke prototypes cavities
  - first tests with the AMC proof of concept prototype with one carrier and 3 daughter boards,
  - operation with 2 channels and -/+80V voltage range
  - first full-scale (RTM board and external PS) prototype used for spoke and H-Beta prototype testing
- Final prototype installed and evaluated **@ESS-TestStand2** 
  - Single piezo-driver for full cryo-module operation (4 cavs.)
  - channels configuration (single/two cavities operation) possible thanks to the piezo split-box,
  - operation with full 0 to 200V or asymmetric configuration possible,
  - full integration with the HW infrastructure and control system (IOC installed and running)

# • in everyday use by the TS2 operators.

# Cavities parameters evaluation

- Thanks to the integrated acquisition system, following studies are being performed :
- main cavity mechanical mode determination from the RF pulse excitation response,
- various mechanical modes o fthe system determination with dedicated mechanical excitation patterns,

Figure 3: Piezo driver

installation in the rack

- piezo capacitance measurement,
- piezo tuning range and hysteresis,







#### Final result: Success

RTM\_HW\_ID: 472 HPD\_HD\_ID: B026 PPSM HW ID: A016 ESS LOCATION ID: MBL040E02 STACK: A





Figure 14: Exemplary report from cavity simulator based DC scan test

# Summary

- PD prototypes tested with all types of superconducting cavities (for ESS),
- Support in the piezo control algorithm implementation
- Software preparation for piezo/cavity automatic parameters identification
- Mass production of the Spoke/Medium Beta/High Beta finish despite semiconductor crisis impact (approx. one year delay),
- Successful installation in the ESS accelerator gallery with initial verification
- ongoing tests with the cavity simulator last verification step.

### References

# • The installation for Spoke (352 MHz) cavities LLRF systems has been completed,

- The installation for M-Beta (704MHz) cavities LLRF systems has been completed,
- The installation for first 20 H-Beta cavities LLRF systems has been completed,
- All installed systems pass visual verification,
- The local excitation/readout tests have been performed for all installed entities,
- Local tests revealed problems with one driver and 2 PPSM - replaced and repaired at DMCS,
- Tests of the DC scan and AC pulse with cavity simulator are in progress and will be concluded in Q1.2024



Figure 6: Cavity (M-Beta) oscillations registered by the piezo sensor during open loop operation



Figure 7: Cavity (M-Beta) free oscillations other module

Figure 8: Spoke cavity mechanical response measured by sensor (chirp signal)



Figure 9: Tuning range measured for spoke cav.

D. Makowski, A. Mielczarek , et. all, (2019). Piezo Control Device In Kind Contribution of PEG Consortium. ESS-ERIC submodule specification.

🔋 W. Cichalewski, G. Jablonski, K. Klys, D. Makowski, A. Mielczarek, A. Napieralski, P. Perek, P. Plewinski, A. Abramowicz, K. Czuba, M. Grzegrzolka, K. Oliwa, I. Rutkowski, W. Wierba, P. Bartoszek, K. Chmielewski, Z. Golebiewski, K. Kostrzewa, T. Kowalski, D. Rybka, M. Sitek, J. Szewinski, Z. Wojciechowski, M. Jensen, A. Svensson, A. Johansson (2022). PEG Contribution to the LLRF System for Superconducting Elliptical Cavities of ESS Accelerator Linac. IPAC 2022, TUPOST017, Bangkok, Thailand.

### Acknowledgments

Work supported by Polish Ministry of Education and Science, agreement number 2021/WK/04

