

전자석의 이해

Understanding of Magnets

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Outline

- Part1: Introduction
 - Magnets
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Part1: Introduction

Magnets

(Particle) accelerators and (electro-) magnets

Magnetic field

Magnet (자석)

Magnēsia (Μαγνησία)

Greek region

Magnétis (Magnesian stone)

Ancient Greek

Magnete

Old French & middle English

- Definition
 - A magnet is a *material* or *object* that **produces a magnetic field.**
- Magnets types by materials
 - Permanent magnet
 - 영구자석, 자석
 - ~1.4 T
 - Electromagnet (**iron-dominated magnet**)
 - 전자석, 상전도 전자석, 상전도 자석, 자석
 - ~2 T
 - <10 A/mm² for the most water-cooling magnets
 - Low/medium energy particle accelerators
 - Superconducting magnet
 - 초전도 전자석, 초전도 자석, 자석
 - >2 T
 - >100 A/mm²
 - High energy particle accelerators

Introduction: (Particle) Accelerators and Magnets

Particle Accelerators → Particle motion → Force

m

a

{
Bending
Focusing/defocusing
Correcting

<Lorentz Force>

$$\mathbf{F} = m\mathbf{a} = q\mathbf{E} + q\mathbf{v} \times \mathbf{B}$$

Electric field
(전기장)

Magnetic field
(자기장)

←
Magnet
(자석)

Magnetic field? B? H?

B [T = Wb/m²]

H [A/m]

https://en.wikipedia.org/wiki/Magnetic_field

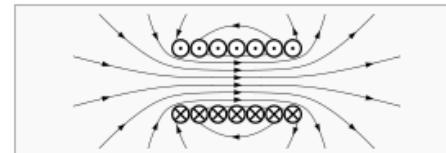
자기장

A 103개 언어 ▾

위키백과, 우리 모두의 백과사전.

자기장(磁氣場, 영어: magnetic field)이란 자석이나 전류에 의해 자기력이 작용하는 공간, 자기력을 매개하는 벡터장이다. 고전적으로는 움직이는 전하, 즉 전류에 의하여 발생하나, 양자역학에서는 입자 고유의 스플도 전류와 같은 역할을 할 수 있다. (이에 따라 강자성체가 영구자성을 가질 수 있다.) 자기장의 방향은 자기장 안에 있는 나침반이 가리키는 방향과 같다. 또한 자기장의 방향을 연속적으로 이은 선의 간격이 촘촘할수록 자기장의 세기가 세다.

고전 전자기학



Alternative names for H^[8]

- Magnetic field intensity^[9]
- Magnetic field strength
- **Magnetic field**
- Magnetizing field

Alternative names for B^[8]

- Magnetic flux density
- Magnetic induction^[9]
- **Magnetic field (ambiguous)**

Magnetic field? B? H? (2)

기호와 용어 [편집]

"자기장"이라고 불리는 장은 **B**와 **H** 두 개가 있다. 이 중 **B**는 자속 밀도(자기장)(磁氣線束密度, magnetic flux density)이라 불리고, **H**는 자계 강도(magnetic field strength)라고 부른다. 두 장은 진공에서는 서로 $\mathbf{B} = \mu_0 \mathbf{H}$ 로 서로 비례하지만, 매질 안에서는 일반적으로 서로 다르다. 자속 밀도와 자계 강도가 서로 비례하는 매질을 선형 매질이라고 하는데, 이 때 비례 상수를 매질의 투자율 μ 이라고 한다.

$$\mathbf{B} = \mu \mathbf{H}$$

국제단위계에서, 자속 밀도 **B**의 단위는 테슬라(T)이고, 자계 강도 **H**의 단위는 암페어 퍼미터(A/m)이다. CGS 단위계에서, **B**의 단위는 가우스(G)이고, **H**의 단위는 에르스忒트(Oe)이다.

과거에는 보통 "자기장"이라고 하면 **H**를 일컬었으나, 오늘날에는 **B**가 로伦즈 힘을 매개하는 더 근본적인 장이므로 보통 **B**를 "자기장"이라고 부른다. 예를 들어, 에드워드 밀스 퍼셀은 저서 《전기와 자기》^[1]에 다음과 같이 적었다.

심지어 **B**를 기본 장으로 다루는 최근 저자들마저도 이를 "자기장"이라고 부르지 않는 경우가 있는데, 이는 역사적으로 "자기장"이라는 이름을 **H**가 찬탈했기 때문이다. 이는 서투르고 고지식해 보인다. [...] 우리는 **B**를 계속 "자기장"이라고 일컬을 것이다. **H**의 경우에는 (다른 이름들도 제시된 바 있지만) 우리는 그냥 "**H**장" 또는 "**H** 자기장"으로 부르겠다.

여기서는 현대적 용법을 따라 **B**장을 "자기장"이라 부르도록 한다.

https://en.wikipedia.org/wiki/Magnetic_field

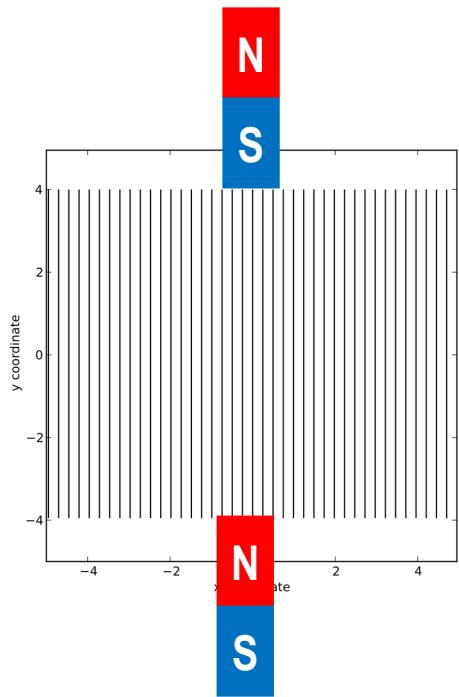
Magnitude of Magnetic Fields

- **31-58 μT** : *Earth magnetic field at 0° latitude*
- **0.5 mT**: the suggested exposure *limit* for *cardiac pacemakers* by American Conference of Governmental Industrial Hygienists (ACGIH)
- **5 mT**: the strength of a typical *refrigerator magnet* or Apple iPhone *Magsafe*
- **1.5 T to 3 T**: strength of medical magnetic resonance imaging (*MRI*) systems in practice, experimentally up to 8 T
- **9.4 T**: modern high resolution research *MRI* system
- **16 T**: strength used to *levitate a frog*
- **41.4 T**: strongest continuous magnetic field produced by non-superconductive *resistive magnet* (32 MW)
- **~~45 T~~**: strongest continuous magnetic field yet produced in a laboratory
(National High Magnetic Field Laboratory in Tallahassee, USA)
 - **45.5 T** achieved by S. Hahn with NHMFL
- Pulse magnets
 - **100.75 T**: strongest (pulsed) magnetic field yet obtained *non-destructively* in a laboratory (NHMFL, Los Alamos National Laboratory, USA)
 - **730 T**: strongest pulsed magnetic field yet obtained in a laboratory, *destroying* the used equipment, but not the laboratory itself (Institute for Solid State Physics, Tokyo)
 - **2.8 kT**: strongest (pulsed) magnetic field ever obtained (with explosives) in a laboratory (VNIIEF in Sarov, Russia, 1998)

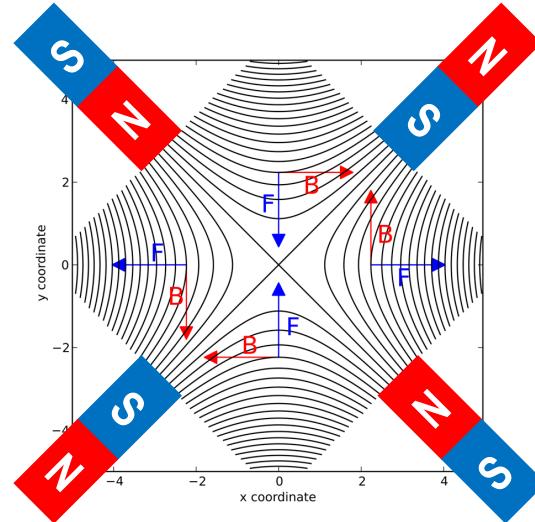
Part2: Accelerator Magnets

Multipole Magnets

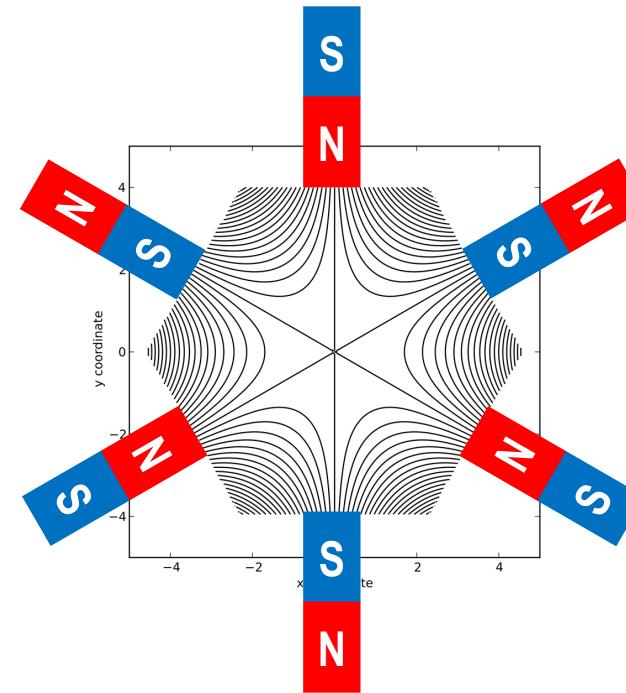
- “Multi”pole Magnets



di-: 2



quadro-: 4



hexa-: 6
(sextupole)

Magnet Types by Shapes and Functions

- The conventional (**iron-dominated**) magnets described herein are those whose **fields are shaped by iron poles**, where the maximum field level in the yoke is **less than the iron saturation level (1.6-2.2 T)** and whose excitation is provided by current carrying coils.
REF: "Iron Dominated Electromagnets", Jack Tanabe
- The iron dominated magnets
 - **Dipoles**
 - *Bending* the particle trajectory
 - **Quadrupoles**
 - *Focusing* and *defocusing* the charged particle beam
 - **Sextupoles**
 - Control (*correction*) of *chromatic aberrations*
 - **Correctors**
 - Vertical and horizontal steering (small angle correction)
 - Skew Quadrupoles
 - Specialized magnets
 - Gradient magnets (a specialized dipole)
 - Current Sheet Septum (Horizontal bend)
 - Lambertson Septum (Vertical bend)
 - Bump and Kicker Magnets
- Air-core magnets
 - **Solenoid**

Maxwell's Magnet (Steady State) Equations

$$\left\{ \begin{array}{l} \nabla \times \mathbf{B} = \mu \mu_0 \mathbf{J} \\ \nabla \times \mathbf{B} = 0 \quad (\text{in the absence of the sources}) \end{array} \right.$$

$$\nabla \cdot \mathbf{B} = 0$$

$$\mathbf{B} = \nabla \times \mathbf{A} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_x & A_y & A_z \end{vmatrix}$$

$$\mathbf{B} = -\nabla V = -\hat{x} \frac{\partial V}{\partial x} - \hat{y} \frac{\partial V}{\partial y} - \hat{z} \frac{\partial V}{\partial z}$$

REF: Electromagnetics (전자기학) textbook

⇒

$$\nabla^2 F = \mu \mu_0 \mathbf{J} \quad \text{Poisson's Eq.}$$

$$\nabla^2 F = 0 \quad \text{Laplace's Eq.}$$

⇒

$$\frac{\partial B_x}{\partial x} + \frac{\partial B_y}{\partial y} + \frac{\partial B_z}{\partial z} = 0$$

A function of complex variable, F :

$$F = \mathbf{A} + iV$$

\mathbf{A} : the vector potential

V : the scalar potential

- An ideal pole contour can be computed using the scalar equipotential.
- The field shape can be computed using the vector equipotential.

Maxwell's Magnet (Steady State) Equations (2)

$$\nabla \times \mathbf{B} = 0 \quad (\text{no sources}) \quad \Rightarrow \text{Assuming that the Coulomb condition, } \nabla \cdot \mathbf{A} = 0$$

$$\mathbf{B} = \nabla \times \mathbf{A}$$

$$\nabla \times \mathbf{B} = \nabla \times (\nabla \times \mathbf{A}) = \nabla(\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A} = -\nabla^2 \mathbf{A} = 0 \quad \Rightarrow \quad \boxed{\nabla^2 \mathbf{A} = 0}$$

Vector identity

$$\nabla \cdot \mathbf{B} = 0$$

$$\mathbf{B} = -\nabla V = -\hat{x} \frac{\partial V}{\partial x} - \hat{y} \frac{\partial V}{\partial y} - \hat{z} \frac{\partial V}{\partial z} \quad \Rightarrow \quad \nabla \cdot \mathbf{B} = -\nabla^2 V = 0 \quad \Rightarrow \quad \boxed{\nabla^2 V = 0}$$

The function, $F = \mathbf{A} + iV$ must also satisfy the Laplace equation

$$\boxed{\nabla^2 F = 0}$$

The Two-Dimensional Fields

- The function: $\underline{F} = \underline{\mathbf{A}} + i\underline{V}$

vector
potential

scalar
potential

$$\mathbf{B} = \nabla \times \mathbf{A} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ A_x & A_y & A_z \end{vmatrix}$$

$$\mathbf{B} = -\nabla V = -\hat{x} \frac{\partial V}{\partial x} - \hat{y} \frac{\partial V}{\partial y} - \hat{z} \frac{\partial V}{\partial z}$$

Two-dimensional field assumption

$$\mathbf{B} = \nabla \times \mathbf{A} = +\hat{y} \left(\frac{\partial B_x}{\partial z} - \frac{\partial B_z}{\partial x} \right) + \hat{z} \left(\frac{\partial B_y}{\partial x} - \frac{\partial B_x}{\partial y} \right) = \mu \mu_0 (\hat{x} J_x + \hat{y} J_y + \hat{z} J_z)$$

3-dimensional form

$$\frac{\partial B_y}{\partial x} - \frac{\partial B_x}{\partial y} = \mu \mu_0 J_z$$

: two-dimensional magnetic fields (satisfy the scalar equation).
 (x, y) plane

Fundamental Relationships

[Euler's identity - Wikipedia](#)

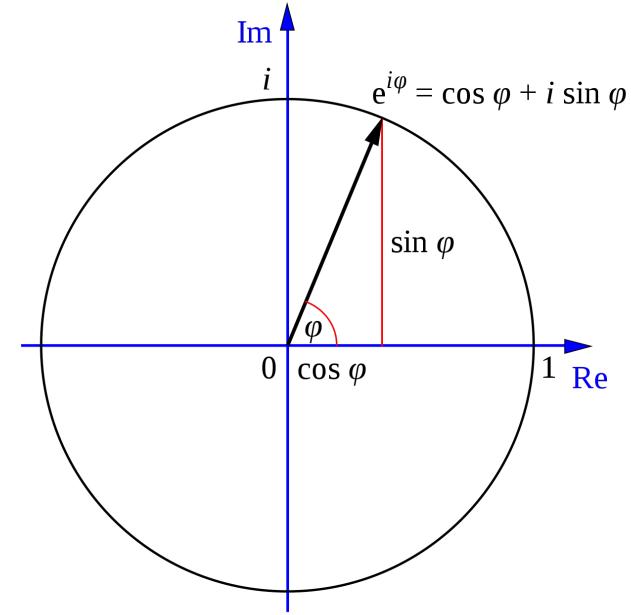
- Geometric interpretation
 - The any complex number $z (= x + iy)$ can be represented by the point (x, y) on the complex plane.
 - In polar coordinate, the point can be represented as (r, θ) .

$$z = x + iy = re^{i\theta} = r(\cos \theta + i \sin \theta)$$

$$|z| = \sqrt{x^2 + y^2} = r$$

, where:

$$\theta = \tan^{-1} \frac{y}{x}$$



Fields from the Two-Dimensional Function of a Complex Variable

$$F = A + iV \quad \Rightarrow \quad \mathbf{B}?$$

$$B^* = B_x - iB_y = iF'(z) = i \frac{dF}{dz} = i \left(\frac{\partial F}{\partial x} \frac{dx}{dz} + \frac{\partial F}{\partial y} \frac{dy}{dz} \right) = i \left(\frac{\partial F}{\partial x} - \frac{\partial F}{\partial y} i \right) = \boxed{\frac{\partial F}{\partial y}} + i \boxed{\frac{\partial F}{\partial x}}$$
$$\begin{matrix} B_x & B_y \end{matrix}$$

$$B_x = \frac{\partial F}{\partial y}$$

$$B_y = -\frac{\partial F}{\partial x}$$

$$\boxed{\frac{\partial B_y}{\partial x} - \frac{\partial B_x}{\partial y} = \mu\mu_0 J_z}$$

 \Rightarrow

$$\boxed{\frac{\partial^2 F}{\partial x^2} + \frac{\partial^2 F}{\partial y^2} = -\mu\mu_0 J_z}$$

Poisson's Equation

Two-Dimensional Fields in a Vacuum

$$\frac{\partial^2 F}{\partial x^2} + \frac{\partial^2 F}{\partial y^2} = -\mu\mu_0 J_z$$

Poisson's Equation

in the magnet (pole) gaps
no current sources
& permeable materials

$$\nabla^2 F = \frac{\partial^2 F}{\partial x^2} + \frac{\partial^2 F}{\partial y^2} = 0$$

Laplace's Equation

Let's find the solution of the Laplace Equation.

$$\frac{\partial F}{\partial x} = \frac{dF}{dz} \frac{dz}{dx} = \frac{dF}{dz}$$

$$\frac{\partial F}{\partial y} = \frac{dF}{dz} \frac{dz}{dy} = \frac{dF}{dz} i$$

$$\frac{\partial^2 F}{\partial x^2} = \frac{\partial}{\partial x} \frac{\partial F}{\partial x} = \frac{\partial}{\partial x} \frac{dF}{dz} = \boxed{\frac{d^2 F}{dz^2}}$$

$$\frac{\partial^2 F}{\partial y^2} = \frac{\partial}{\partial y} \frac{\partial F}{\partial y} = \frac{\partial}{\partial y} \frac{dF}{dz} i = \frac{d^2 F}{dz^2} i \frac{\partial z}{\partial x} = \frac{d^2 F}{dz^2} i^2 = \boxed{-\frac{d^2 F}{dz^2}}$$

$$z = x + iy$$
$$\frac{dx}{dz} = 1 \quad \frac{dy}{dz} = -i$$

$$\nabla^2 F = \frac{\partial^2 F}{\partial x^2} + \frac{\partial^2 F}{\partial y^2} = \frac{\partial^2 F}{\partial z^2} - \frac{\partial^2 F}{\partial z^2} = 0$$

Solution to Laplace's Equation and Ideal “Multipoles”

$$\nabla^2 F = \frac{\partial^2 F}{\partial x^2} + \frac{\partial^2 F}{\partial y^2} = \frac{\partial^2 F}{\partial z^2} - \frac{\partial^2 F}{\partial z^2} = 0$$

Laplace's Equation

$$F = A + V$$

Solution

$$F = Cz^n$$

in another form

$$z = x + iy = |z|e^{i\theta}$$

<Ideal Two-Dimensional “Multipole” Magnets>

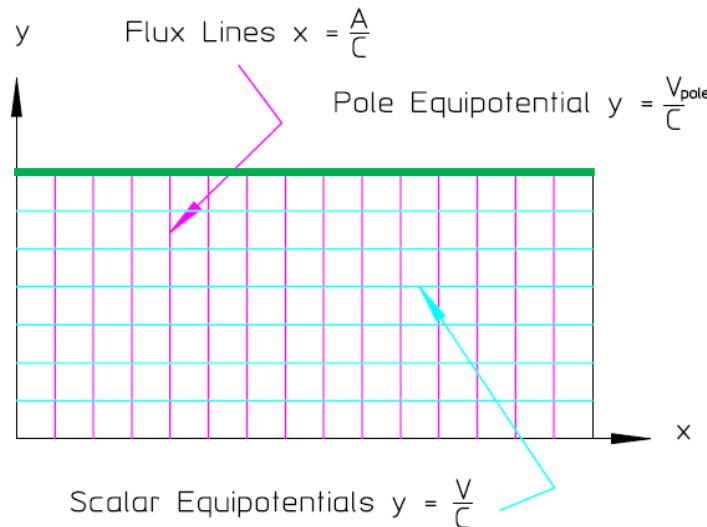
$$F = Cz^n \quad \left\{ \begin{array}{ll} n = 1 & \Rightarrow F = C_1 z^1 \quad \text{Dipole} \\ n = 2 & \Rightarrow F = C_2 z^2 \quad \text{Quadpole} \\ n = 3 & \Rightarrow F = C_3 z^3 \quad \text{Sextupole (Hexapole)} \\ n = 4 & \Rightarrow F = C_4 z^4 \quad \text{Octopole} \\ \dots & \Rightarrow F = C_n z^n \quad \text{2n-pole} \end{array} \right.$$

Dipole Magnets ($n = 1$)

$$\mathbf{F} = C_1 \mathbf{z} = C_1(x + iy) = A + iV$$

$$x = \frac{A}{C_1} \quad : \text{Vector equipotential}$$

$$y = \frac{V}{C_1} \quad : \text{Scalar equipotential}$$

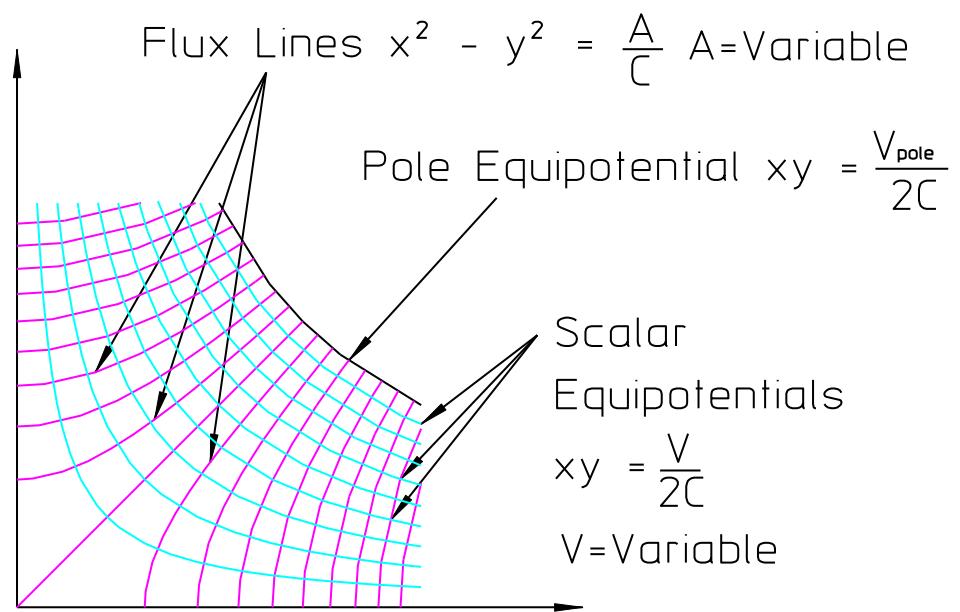


Quadrupole Magnets ($n = 2$)

$$F = C_2 z^2 = C_2(x + iy)^2 = C_2(x^2 - y^2 + i2xy) = A + iV$$

$$x^2 - y^2 = \frac{A}{C_2}$$

$$xy = \frac{V}{2C_2}$$



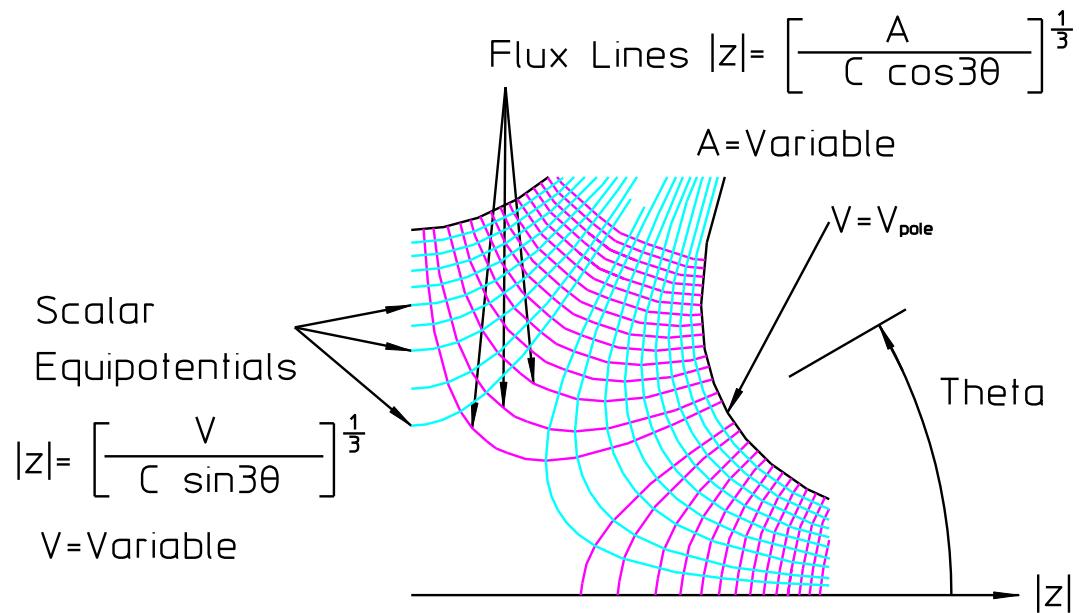
Sextupole Magnets ($n = 3$) in polar coordinates

$$F = C_3 z^3 = C_3(x + iy)^3 = C_3(x^3 - 3xy^2) + iC_3(3xy^2 - y^3) = A + iV$$

$$= C_3|z|^3 e^{i3\theta} = C_3|z|^3(\cos 3\theta + i \sin 3\theta) = A + iV$$

$$x^3 - 3xy^2 = \frac{A}{C_3}$$

$$3xy^2 - y^3 = \frac{V}{C_3}$$



“Real” Multipole Magnets with Multipole Errors

$$F = Cz^n$$

(Ideal) solution of the Laplace Eq.

→ Ideal multipole magnets ($n = 1, 2, 3, \dots$)

$$F = \Sigma Cz^n$$

Taylor expansion of the function F

→ must also satisfy the Laplace's equation.

$$F = C_1 z^1 + C_2 z^2 + C_3 z^3 + C_4 z^4 + \dots$$

$N = 1$ (dipole)

$$F = C_1 z^1 + \sum_{n \neq 1} C_n z^n$$

$N = 2$ (quadrupole)

$$F = C_2 z^2 + \sum_{n \neq 2} C_n z^n$$

General form (N -pole)

$$F = C_N z^N + \sum_{n \neq N} C_n z^n$$

Fundamental (desired) field component

Multipole error (undesired) component

Magnetic Field from $F(z)$

(1) Dipole Field

$$F = A + iV = C_n z^n \quad \Rightarrow \quad \mathbf{B}?$$

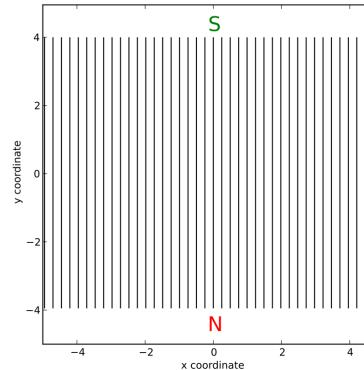
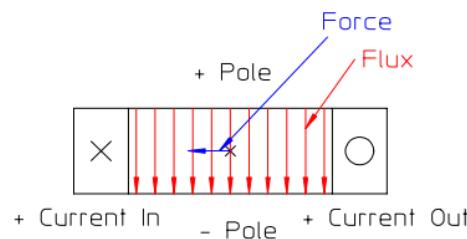
$$B^* = B_x - iB_y = iF'(z) = i \frac{\partial(C_n z^n)}{\partial z} = i n C_n z^{n-1}$$

$n = 1$: dipole magnet

$$B_{1x} = 0$$

$$B_1^* = B_{1x} - iB_{1y} = iC_1$$

$$B_{1y} = -C_1$$



Magnetic Field from $F(z)$

(2) Quadrupole Field

$$F = A + iV = C_n z^n \quad \Rightarrow \quad \mathbf{B}?$$

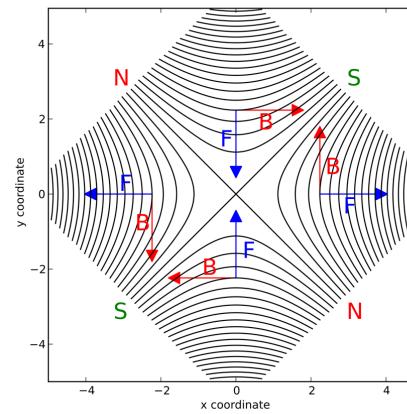
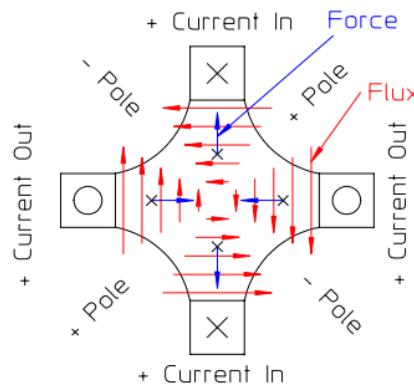
$$B^* = B_x - iB_y = iF'(z) = i \frac{\partial(C_n z^n)}{\partial z} = i n C_n z^{n-1}$$

$n = 2$: quadrupole magnet

$$B_2^* = B_{2x} - iB_{2y} = i2C_2 z = i2C_2(x + iy) = -2C_2 y + i2C_2 x$$

$$B_{2x} = -2C_2 y$$

$$B_{2y} = -2C_2 x$$



Magnetic Field from $F(z)$

(3) Sextupole Field

$$F = A + iV = C_n z^n \quad \Rightarrow \quad \mathbf{B}?$$

$$B^* = B_x - iB_y = iF'(z) = i \frac{\partial(C_n z^n)}{\partial z} = inC_n z^{n-1}$$

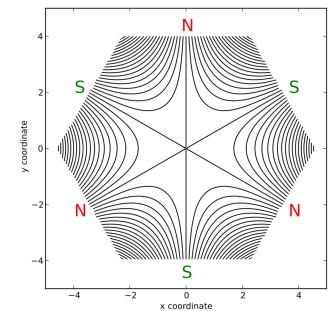
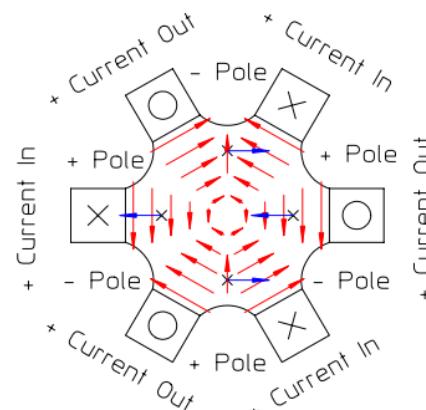
$n = 3$: sextupole magnet

$$\begin{aligned} B_3^* &= B_{3x} - iB_{3y} = i3C_3 z^2 = i3C_3(x + iy)^2 = i3C_3(x^2 - y^2 + i2xy) \\ &= i3C_3|z|^2 e^{i2\theta} = i3C_3|z|^2(\cos 2\theta + i \sin 2\theta) \end{aligned}$$

$$B_{3x} = -6C_3 xy = -3C_3|z|^2 \sin 2\theta$$

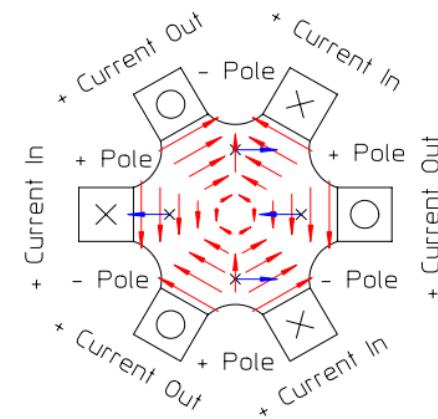
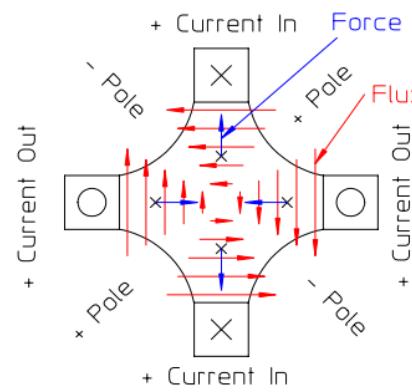
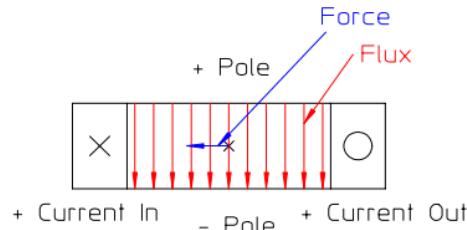
$$B_{3y} = 3C_3(x^2 - y^2) = -3C_3|z|^2 \cos 2\theta$$

$$B_{3r} = B_{3x} \cos \theta + B_{3y} \sin \theta = -3C_3|z|^2 \sin 3\theta$$



Conventions

- Current
 - Positive (+) current flows from the positive (+) lead of the power supply to the negative (-) lead.
- Field
 - ○: *out of* the page
 - ×: *into* the page
- Ex: for the positive particle beam



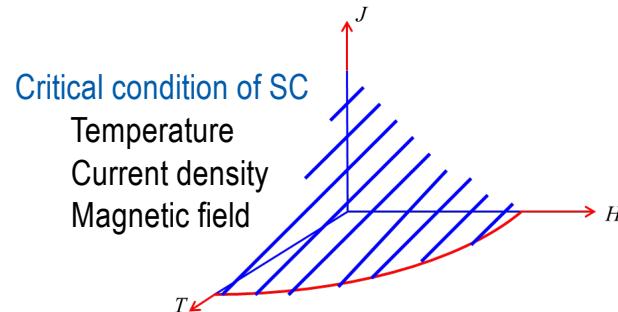
Part3: Superconducting Magnets

Superconductivity

- Superconductivity (science)
 - The set of physical properties observed in certain materials, wherein **electrical resistance vanishes** and from which **magnetic fields (flux) are expelled**.

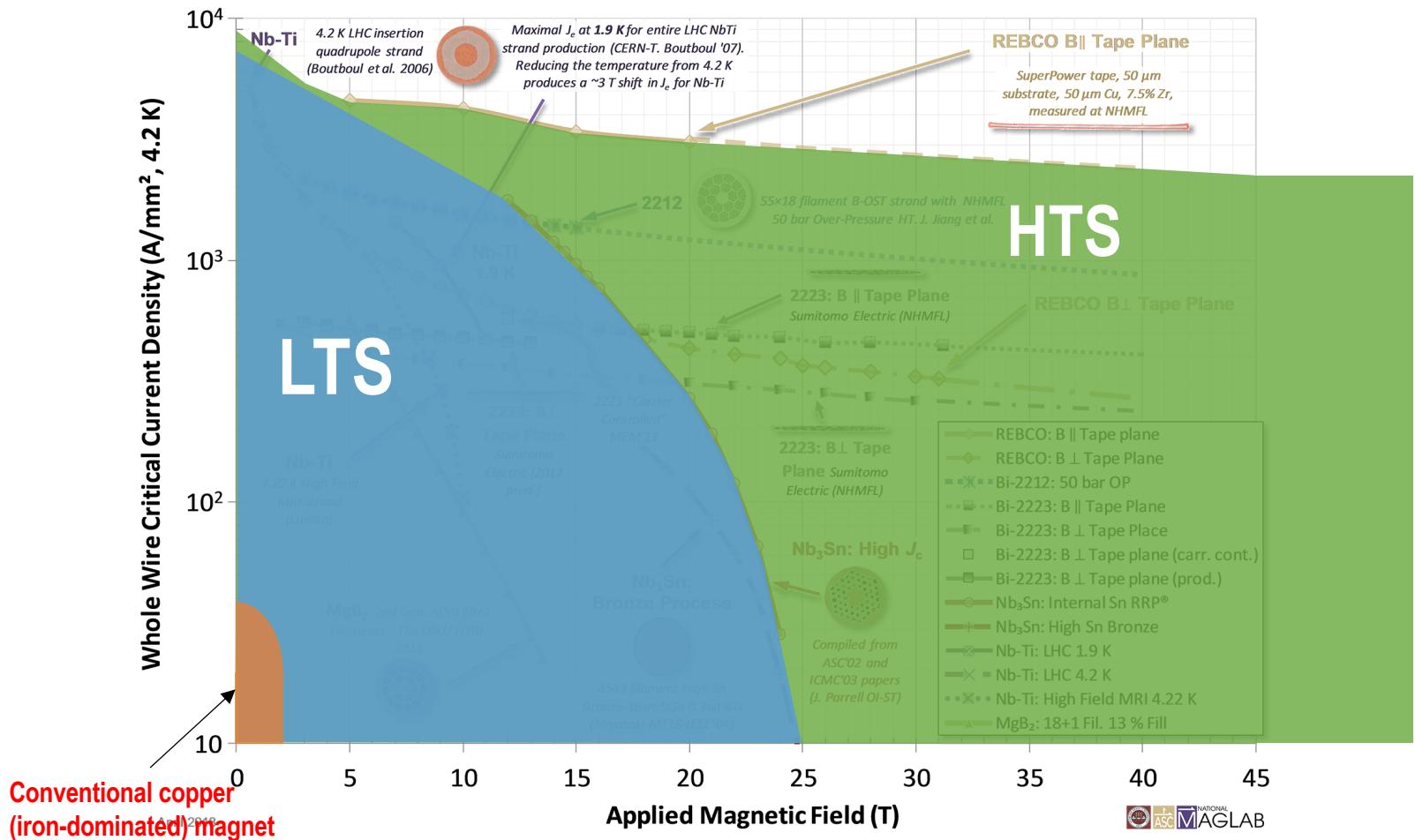
(Perfect) Superconductor: $\rho = 0, B = 0$
Normal conductor: $\rho \neq 0, B \neq 0$

Zero resistance!
Perfect diamagnetism (Meissner effect)!
- Classification of Superconductor
 - Response to a magnetic field: Type I (a single critical field) & Type II (two critical fields)
 - By theory of operation: conventional (explained by BCS theory, $T_c < 40 K$) & unconventional ($T_c \geq 40 K$)
 - By material: chemical elements (mercury or lead), alloys (NbTi, NbGe), ceramics (YBCO and MgB₂), superconducting pnictides (fluorine-doped LaOFeAs), or organic superconductors (fullerenes and carbon nanotubes)
 - [engineering] **By the critical temperature (LTS: <30 K)**
 - **Low-Temperature Superconductor (LTS)**: NbTi (~10 K), Nb₃Sn (18.3 K),
 - **High-Temperature Superconductor (HTS)**: REBCO (YBCO, GdBCO, ~93 K)



Copper vs. LTS vs. HTS

REF: Peter J. Lee, <https://fs.magnet.fsu.edu/~lee/plot/plot.htm>



Why HTS?

- High overall **current density**, $J_e \rightarrow$ more **compact** magnets
- High **stability** (energy) margin (Δe_h) \rightarrow High T_{op} (versus LTS magnets)
- NI or MI REBCO coil \rightarrow Dry winding (no epoxy) \rightarrow Easier fabrication

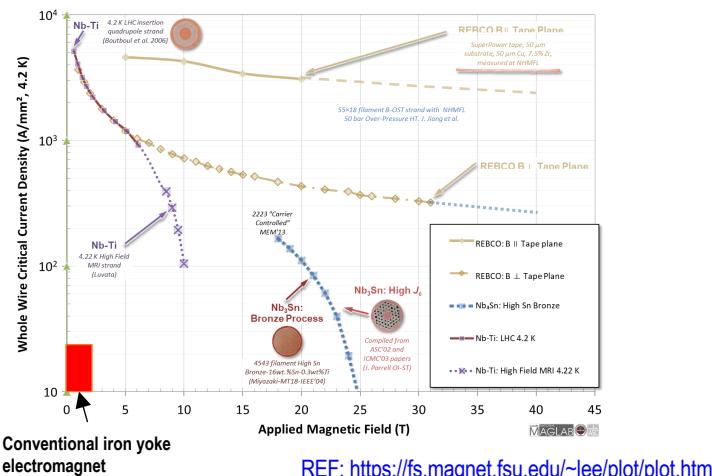


Table 6.4: Selected Values of T_{op} , ΔT_{op} , and Δe_h for LTS and HTS

LTS			HTS		
T_{op} [K]	$[\Delta T_{op}(I_{op})]_{st}$ [K]	Δe_h [J/cm³]	T_{op} [K]	$[\Delta T_{op}(I_{op})]_{st}$ [K]	Δe_h [J/cm³]
2.5	0.3	1.2×10^{-4}	4.2	25	1.6
4.2	0.5	0.6×10^{-3}	10	20	1.8
4.2	2	4.3×10^{-3}	30	10	3.7
10	1	9×10^{-3}	70	5	8.1

REF: Y. Iwasa, Case Studies in Superconducting Magnets (2nd ed.), Ch. 6. Stability, p357